Sequential Path Planning Planning

ECC 2015

* Deterministic formulation
* HJIVI
* 4 Plane deterministic example

CDC 2016

* Disturbance formulation
* HJIVI
* Obstacle generation
* Plane disturbance example
* *Update of reachable sets*

Extra material

* “Optimal” example
* Multiple vehicle types
* Disturbance formulation with state measurement
* Update of reachable sets